

Aufgabe 20

a.) ohne Tilger

$$m_1 \ddot{x}_1 + b_1 \dot{x}_1 + c_1 x_1 = F_1 \cos \Omega t$$

$$\ddot{x}_1 = \frac{1}{m_1} (F_1 \cos \Omega t - b_1 \dot{x}_1 - c_1 x_1)$$

$$\gamma = \begin{pmatrix} \gamma_1 \\ \gamma_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ \dot{x}_1 \end{pmatrix} \quad \dot{\gamma} = \begin{pmatrix} \dot{x}_1 \\ \ddot{x}_1 \end{pmatrix} = \begin{pmatrix} \gamma_2 \\ \frac{1}{m_1} (F_1 \cos \Omega t - b_1 \gamma_2 - c_1 \gamma_1) \end{pmatrix}$$

$\underbrace{\hspace{15em}}_{f_{1d}(t, \gamma)}$

$$\Rightarrow \dot{\gamma} = \begin{pmatrix} \gamma_2 \\ \frac{1}{m_1} (F_1 \cos \Omega t - b_1 \gamma_2 - c_1 \gamma_1) \end{pmatrix}$$

$\underbrace{\hspace{15em}}_{f(t, \gamma)}$

b.) mit Tilger

$$M\ddot{x} + D\dot{x} + Cx = F(t)$$

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$F(t) = \begin{pmatrix} F_1 \\ 0 \\ F_2 \end{pmatrix} \in \mathbb{R}^3$$

$$M\ddot{x} = \hat{F} \in \mathbb{R}^3 - D\dot{x} - Cx \quad | M^{-1}$$

$$\ddot{x} = M^{-1} (\hat{F} \in \mathbb{R}^3 - D\dot{x} - Cx)$$

$$y = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} x_1 \\ \dot{x}_1 \\ x_2 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} x \\ \dot{x} \end{pmatrix}$$

$$\dot{y} = \underbrace{\begin{pmatrix} v \\ M^{-1} (\hat{F} \in \mathbb{R}^3 - Dv - Cx) \end{pmatrix}}_{f(t, y)}$$